

## Introduction

In deformation theory, the following question naturally arises: Given a scheme  $X$  with only *mild* singularities, what can we say about the singularities of local deformations of  $X$ ? For  $X$  containing at worst isolated toric singularities, a conjecture by Riemenschneider formulates a possible answer. If  $X$  is a scheme over a field with characteristic 0, the conjecture is known to be true. However, for schemes over fields of positive characteristic, the conjecture is not yet known.

### Riemenschneiders conjecture

In 1974, Riemenschneider in [Rie74] formulated the following conjecture:

**Local deformations of isolated toric singularities contain at worst toric singularities.**

### Deformations

Let  $X$  be of finite type over  $k$  and  $S$  the spectrum of a local noetherian  $k$ -algebra. A *local deformation* of  $X$  over  $S$  is a pull-back diagram of the form

$$\begin{array}{ccc} X \cong \text{Spec } k \times_S \mathcal{X} & \longrightarrow & \mathcal{X} \\ \downarrow & \lrcorner & \downarrow \pi \\ \text{Spec } k & \longrightarrow & S, \end{array}$$

where  $\pi$  is a flat morphism. If the isomorphism  $X \cong \text{Spec } k \times_S \mathcal{X}$  is clear, we will refer to  $\mathcal{X} \xrightarrow{\pi} S$  as a local deformation.

A local deformation  $\mathcal{X} \xrightarrow{\pi} S$  is called *versal*, if for every other local deformation  $\mathcal{Y} \xrightarrow{\pi'} R$  can be obtained from  $\mathcal{X} \xrightarrow{\pi} S$  by basechange,

$$\begin{array}{ccc} \mathcal{Y} & \longrightarrow & \mathcal{X} \\ \downarrow \pi' & \lrcorner & \downarrow \pi \\ R & \longrightarrow & S. \end{array}$$

### Toric Singularities

Starting with a strongly convex polyhedral cone, an affine toric variety can be constructed in the following way:

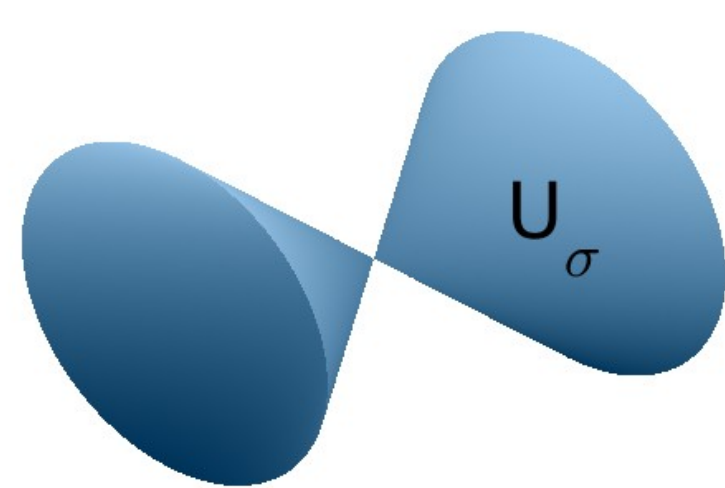
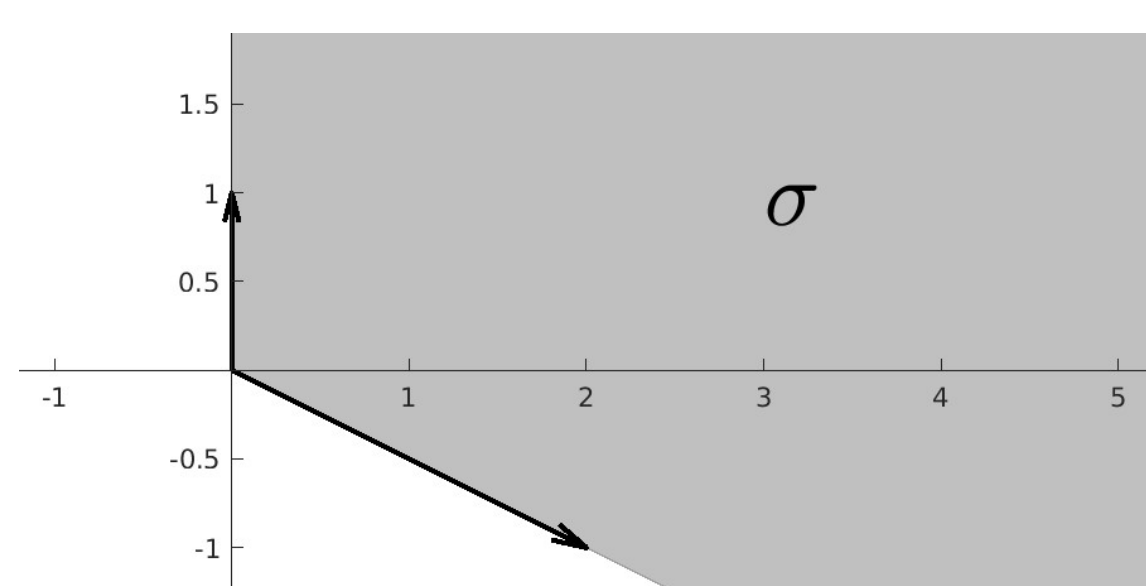
$$\text{cone } \sigma \rightarrow \text{dual cone } \sigma^\vee \rightarrow \text{semigroup } S_\sigma \rightarrow \text{group algebra } k[S_\sigma] \rightarrow \text{affine toric variety } U_\sigma$$

A toric singularity is a singularity occurring in toric varieties.

#### Example.

The  $A_n$  singularities are toric singularities, coming from the two-dimensional cones

$$\sigma = \text{cone} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} n \\ -n+1 \end{pmatrix} \right\} \rightarrow U_\sigma = \text{Spec } k[X, Y, Z] / (XZ - Y^n).$$



The cone and associated affine toric variety with singularity  $A_2$ .

In order to talk about the isolated singularity as it's own algebro-geometric object, we identify it with the spectrum of the completion of it's local ring.

**Example.** Consider the affine toric variety

$$\begin{aligned} \sigma &= \text{cone} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 11 \\ -8 \end{pmatrix} \right\} \\ \rightarrow U_\sigma &= \text{Spec } k[X_1, X_2, X_3, X_4] / (X_1X_3 - X_2^4, X_2X_4 - X_3^3, X_1X_4 - X_2^3X_3^2). \end{aligned}$$

This variety has an isolated singularity at  $(0, 0, 0, 0)$ , namely the singularity

$$X(4, 3) = \text{Spec } k[[X_1, X_2, X_3, X_4]] / (X_1X_3 - X_2^4, X_2X_4 - X_3^3, X_1X_4 - X_2^3X_3^2).$$

Every toric surface can be written as a quotient of a polynomial ring  $k[X_1, \dots, X_e]$  by some ideal  $I$  containing among others some polynomials of the form  $X_1X_3 - X_2^{a_2}, \dots, X_{e-2}X_e - X_{e-1}^{a_{e-1}}$ . The numbers  $a_2, \dots, a_{e-1}$  suffice to specify the toric surface in question and the singularity of the corresponding toric surface is denoted  $X(a_2, \dots, a_{e-1})$ .

Every cyclic quotient singularity is a toric singularity and vice-versa. Therefore, all papers about cyclic quotient singularities can also be read as papers about toric singularities.

### References

- [Arn88] Jürgen Arndt. *Verselle Deformationen zyklischer Quotientensingularitäten*. PhD thesis, Staats-und Universitätsbibliothek Hamburg Carl von Ossietzky, 1988.
- [KSB88] J. Kollár and N. I. Shepherd-Barron. Threefolds and deformations of surface singularities. *Inventiones mathematicae*, 91(2):299–338, Jun 1988.
- [LMM] Christian Liedtke, Gebhard Martin, and Yuya Matsumoto. Linearly reductive quotient singularities. *to appear in Astérisque*.
- [Rie74] Oswald Riemenschneider. Deformationen von Quotientensingularitäten (nach zyklischen Gruppen). *Mathematische Annalen*, 209:211–248, 09 1974.
- [Sch71] Michael Schlessinger. Rigidity of quotient singularities. *Inventiones mathematicae*, 14(1):17–26, Mar 1971.

### History of relevant results

The following table gives an overview of the cases for which Riemenschneiders conjecture has been proven. The last three columns show the dimensions  $d$ , the embedding dimension  $e$ , and the characteristic of the underlying ground field  $\text{char } k$  for which a proof has been found.

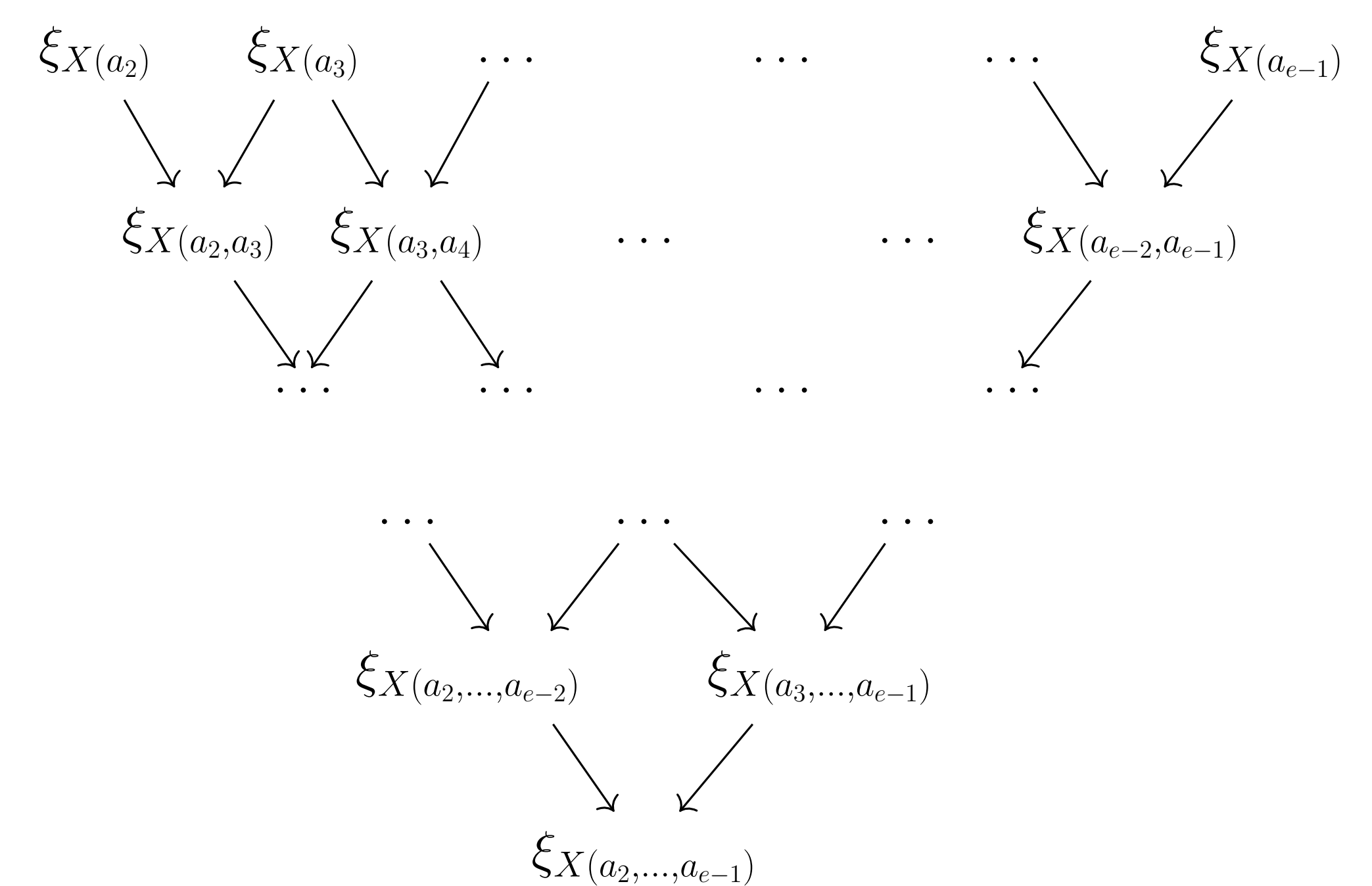
Authors		$d$	$e$	$\text{char } k$
Schlessinger	[Sch71]	$\geq 3$	any	0
Riemenschneider	[Rie74]	2	$\leq 5$	0
Kollár and Shepherd-Barron	[KSB88]	2	any	0
Liedtke, Martin, and Matsumoto	[LMM]	$\geq 3$	any	$> 0$

This means that  $\dim 2, \text{char } > 0$  is still open!

Additionally, in a series of PhD-theses by Arndt, Brohme, and Hamm, an algorithmic construction of versal deformations of toric surface singularities over  $\mathbb{C}$  was found. The versal deformation lets us determine exactly which singularities can be obtained by deforming isolated toric surface singularities.

### Finding versal deformations

The construction of a versal deformation  $\xi_{X(a_2, \dots, a_{e-1})}$  of an isolated toric surface singularity  $X(a_2, \dots, a_{e-1})$  over  $\mathbb{C}$  that was first given by Arndt in [Arn88] is an iterative procedure. Given a singularity  $X(a_2, \dots, a_{e-1})$ , we first construct the versal deformations  $\xi_{X(a_2)}, \dots, \xi_{X(a_{e-1})}$ . In the next step, the versal deformations  $\xi_{X(a_i, a_{i+1})}$  are constructed by combining  $\xi_{X(a_i)}$  and  $\xi_{X(a_{i+1})}$ . Then,  $\xi_{X(a_i, a_{i+1})}$  and  $\xi_{X(a_{i+1}, a_{i+2})}$  can be combined into a versal deformation  $\xi_{X(a_i, a_{i+1}, a_{i+2})}$  and so on, until we have a versal deformation  $\xi_{X(a_2, \dots, a_{e-1})}$ .



### Example

**Example** (Versal deformation of  $X(a_2)$ ). Consider the toric surface singularity  $X(a_2)$  over a field  $k$ . If  $\text{char } k \nmid a_2$ , then a versal deformation of  $X(a_2)$  is given by

$$\xi_{X(a_2)} = \begin{array}{ccc} X(a_2) & \longrightarrow & \text{Spec } k[[t_1, \dots, t_{a_2-1}]] [X, Y, Z] / (XZ - Y^n + \sum_{i=0}^{n-2} t_{i+1} Y^i) \\ \downarrow & & \downarrow \\ \text{Spec } k & \longrightarrow & \text{Spec } k[[t_1, \dots, t_{a_2-1}]]. \end{array}$$

On the other hand, if  $\text{char } k \mid a_2$ , then a versal deformation is given by

$$\xi_{X(a_2)} = \begin{array}{ccc} X(a_2) & \longrightarrow & \text{Spec } k[[t_1, \dots, t_n]] [X, Y, Z] / (XZ - Y^n + \sum_{i=0}^{n-1} t_{i+1} Y^i) \\ \downarrow & & \downarrow \\ \text{Spec } k & \longrightarrow & \text{Spec } k[[t_1, \dots, t_n]]. \end{array}$$

**Note:** The versal deformation is dependent on the characteristic.