# IDP: Development of a Cost Function for RLbased CAM Planning

### **Motivation**

The quality of CAM planning is often heavily influenced by the experience and intuition of the programmer, making it highly subjective. This thesis aims to reduce that dependency by integrating a reinforcement learning (RL) framework that can optimize CAM strategies automatically. A key component of this is the development of a cost function to objectively evaluate the quality of the generated CAM-based tool paths.

### Scope of Work

The goal is to design and implement a cost function that can be used within an RL environment to assess CAM planning results.

The project includes:

- Designing and implementing an evaluation logic
- Integrating an existing external REST API
- Connecting the cost function to an RL framework

• Testing and analyzing results using example processes

## Requirements

- Master's degree student in mechanical engineering, computer science, mechatronics, or a related field
- Strong programming skills in Python and experience working with APIs
- Desirable: knowledge of reinforcement learning and CAM systems
- Structured and independent working style

### Contact

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